

Uncertainties and Error Propagation

The general method of getting formulas for propagating errors involves the total differential of a function. Suppose that $z = f(w, x, y, \dots)$ where the variables w, x, y , etc. must be independent variables!

The total differential is then

$$dz = \left(\frac{\partial f}{\partial w}\right) dw + \left(\frac{\partial f}{\partial x}\right) dx + \left(\frac{\partial f}{\partial y}\right) dy + \dots$$

We treat the $dw = \Delta w$ as the error in w , and likewise for the other differentials, dz, dx, dy , etc. The numerical values of the partial derivatives are evaluated by using the average values of w, x, y , etc. The general result is

$$\Delta z = \left|\frac{\partial f}{\partial w}\right| \Delta w + \left|\frac{\partial f}{\partial x}\right| \Delta x + \left|\frac{\partial f}{\partial y}\right| \Delta y + \dots$$

Example: Consider $S = x \cos(q)$ for $x = (2.0 \pm 0.2) \text{ cm}$, $q = (53 \pm 2)^\circ = (0.9250 \pm 0.0035) \text{ rad}$. Find S and its uncertainty. Note: the uncertainty in angle must be in radians!

We have that $S = 2.0 \cos(53^\circ) = 1.204 \text{ cm}$

The total differential is found by deriving S with respect to x and to θ . It leads to

$$dS = \cos(\theta) dx - x \sin(\theta) d\theta$$

We take the absolute value of each term.

$$\Delta S = \cos(\theta) \Delta x + x \sin(\theta) \Delta \theta = 0.126 \text{ cm}$$

Hence $S = (1.20 \pm 0.13) \text{ cm}$.